#Jenny

Finally I get this ebook, thanks for all these I can get now!

#Rio

Cool! I'am really happy

#Markus Jensen

I did not think that this would work, my best friend showed me this website, and it does! I get my most wanted eBook

#Hun Tsu

wtf this great ebook for free?!

#Che Salsa

My friends are so mad that they do not know how I have all the high quality ebook which they do not!

#Diego Butler

so many fake sites. this is the first one which worked! Many thanks

Example

Consider again a problem with two dependent variables $u(x,t)$, $v(x,t)$, and the following PDE system for them

```
> DepVars := {u, v}(x, t)
DepVars := {u, v}(x, t)
> U, V := diff_table(u(x, t)), diff_table(v(x, t)):
> eq1 := U[t] + 1/2*U[]^2 + 2*V[] - 2*x = (1/2*(-V[]^2 + 2*V[x, t]))/V[]^2
eq1 := u_t + 1/2*u^2 + 2*v(x, t) - 2*x = 1/2*(-v_x^2 + 2*v_x)/v^2
> eq2 := V[t] + D/(D(V[], U[])) = 0
eq2 := v_t + v_x/(v_x/v^2*u_x) = 0
> PDESYS := {eq1, eq2}:
> S := InfinitesimalsBasis(PDESYS, DepVars, typeofsymmetry = lie, evolutionary, polynomial, displayfunctionality = false)
S := {xi_x = 0, xi_t = 0, eta_u = 1, eta_v = 0}, {xi_x = 0, xi_t = 0, eta_u = v_x, eta_v = 1}, {xi_x = 0, xi_t = 0, eta_u = 2*t, eta_v = 1}, {xi_x = 0, xi_t = 0, eta_u = -t
   + t*v_x, eta_v = t*v}
```

Note that, as expected, in the result above there are dynamical symmetries (the last three), involving the derivatives u_x, u_t, v_x and v_t.

Dynamical symmetries can also be tested for correctness with SymmetryTest

```
> map(SymmetryTest, S, PDESYS)
{0}, {0}, {0}, {0}
```

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